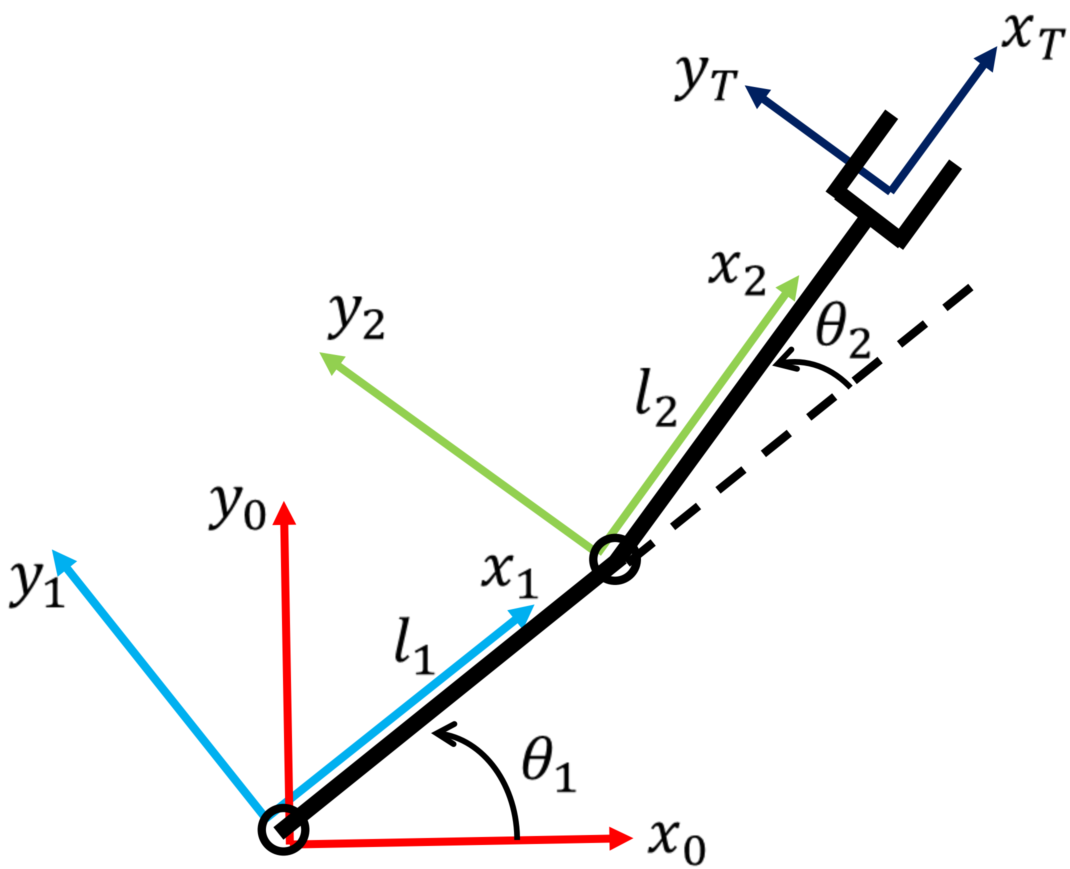
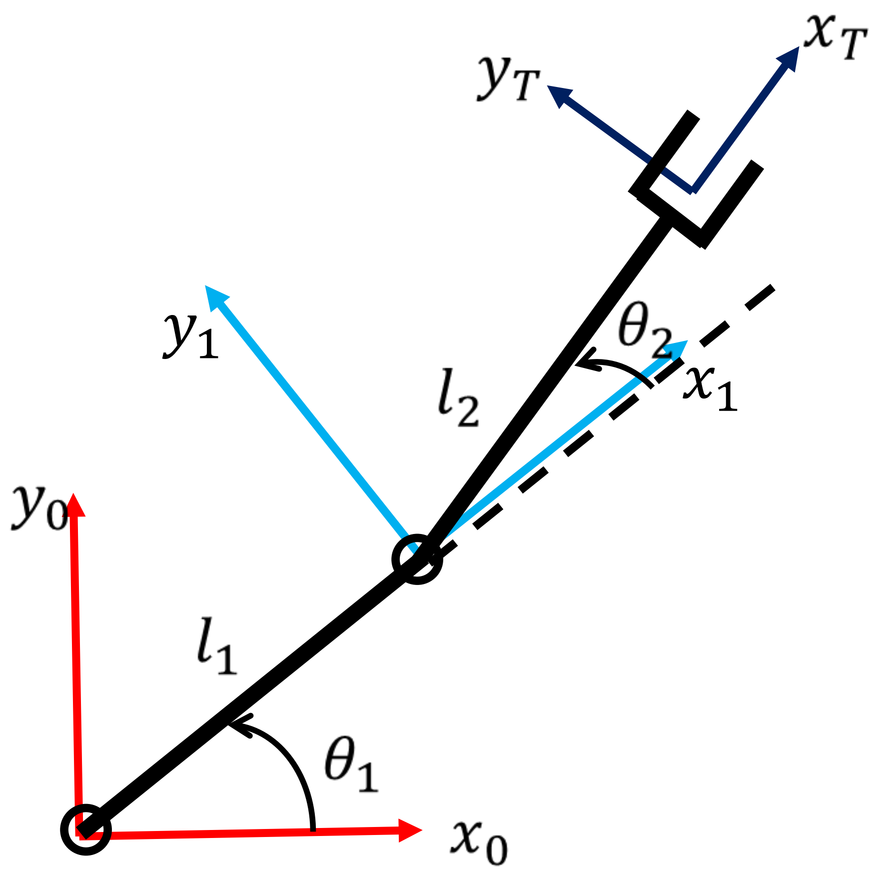
Robotic Arms Library

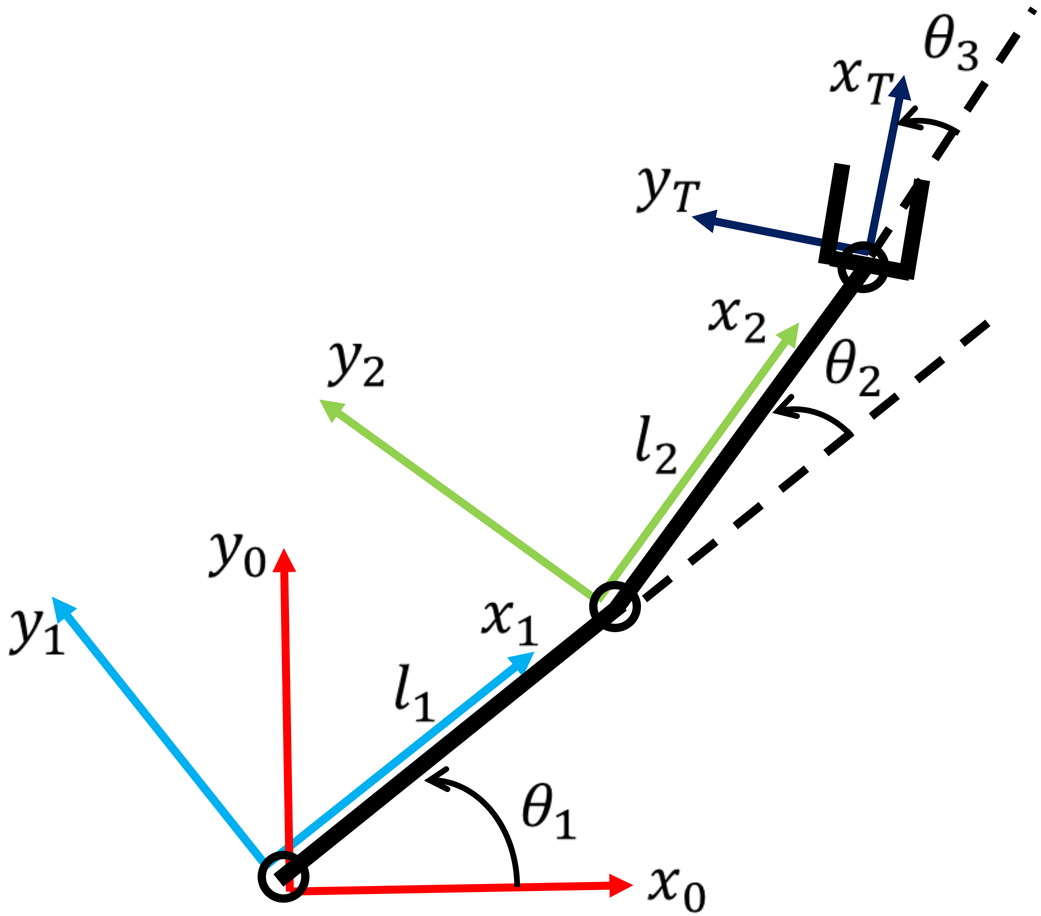
2D – 1 – RR (modified DH)



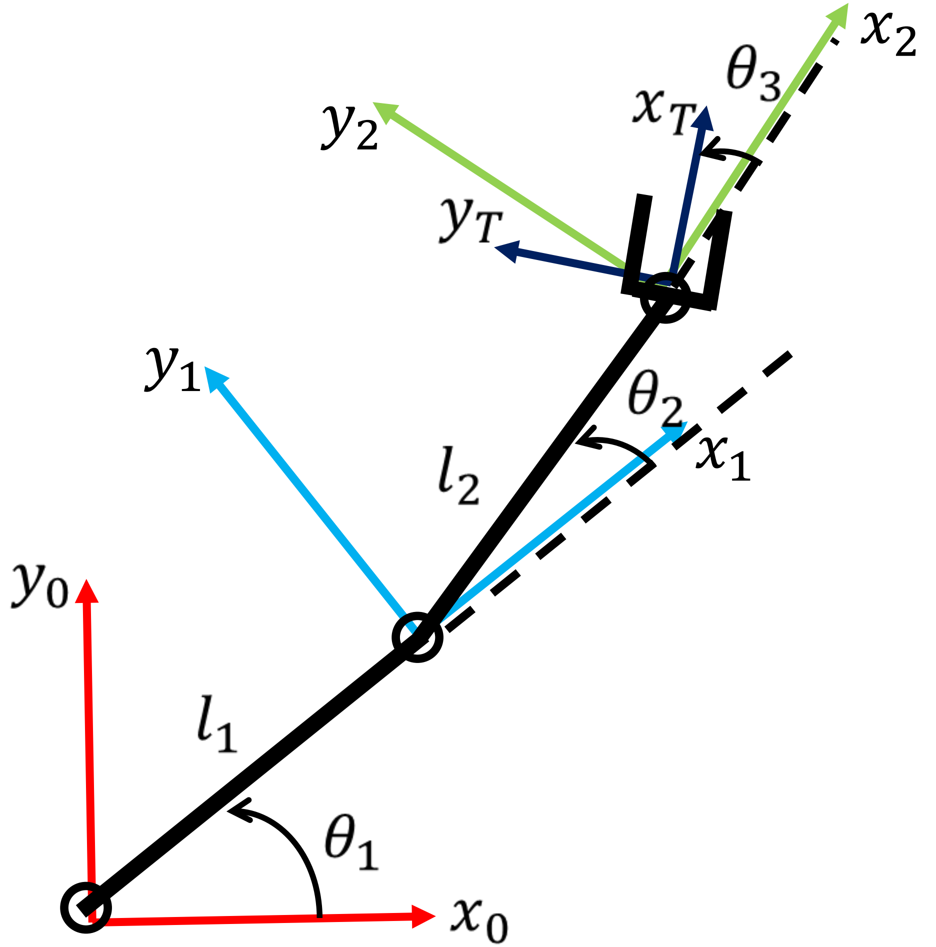
2D – 1 – RR (standard DH)



2D – 2 – RRR (modified DH)

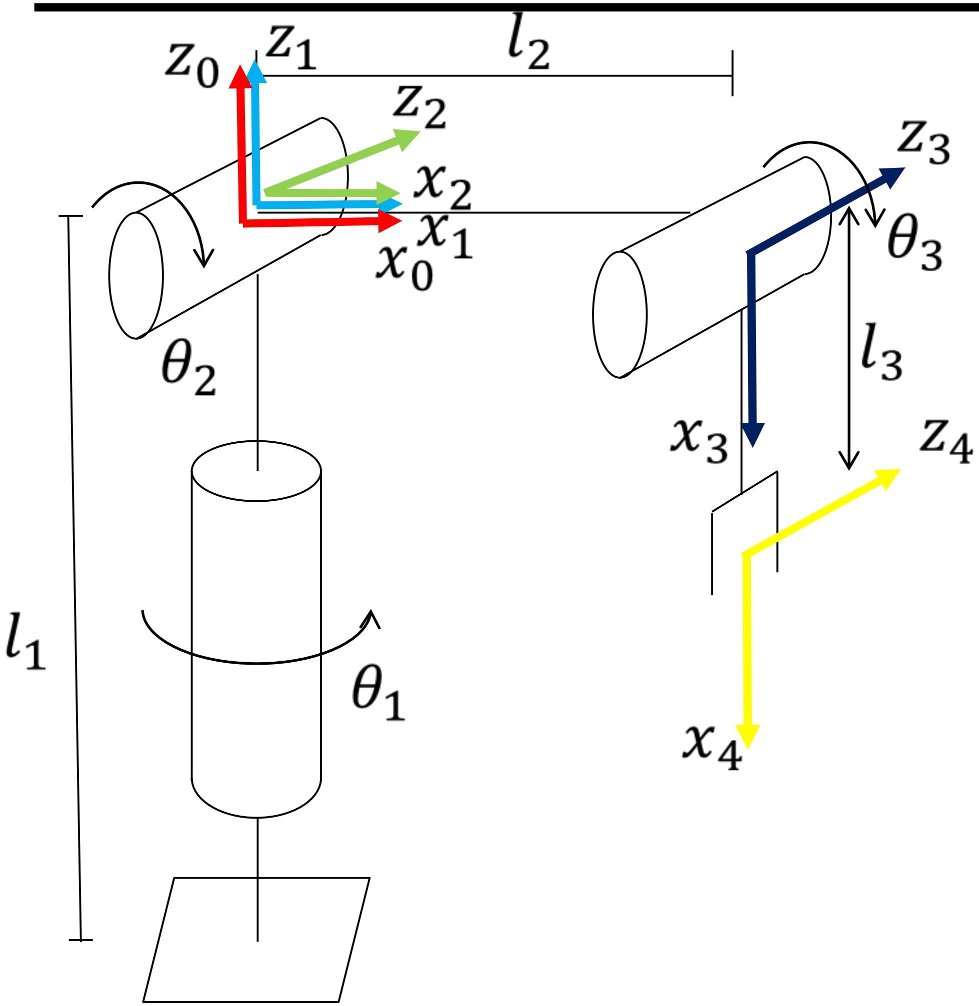


2D – 2 – RRR (standard DH)

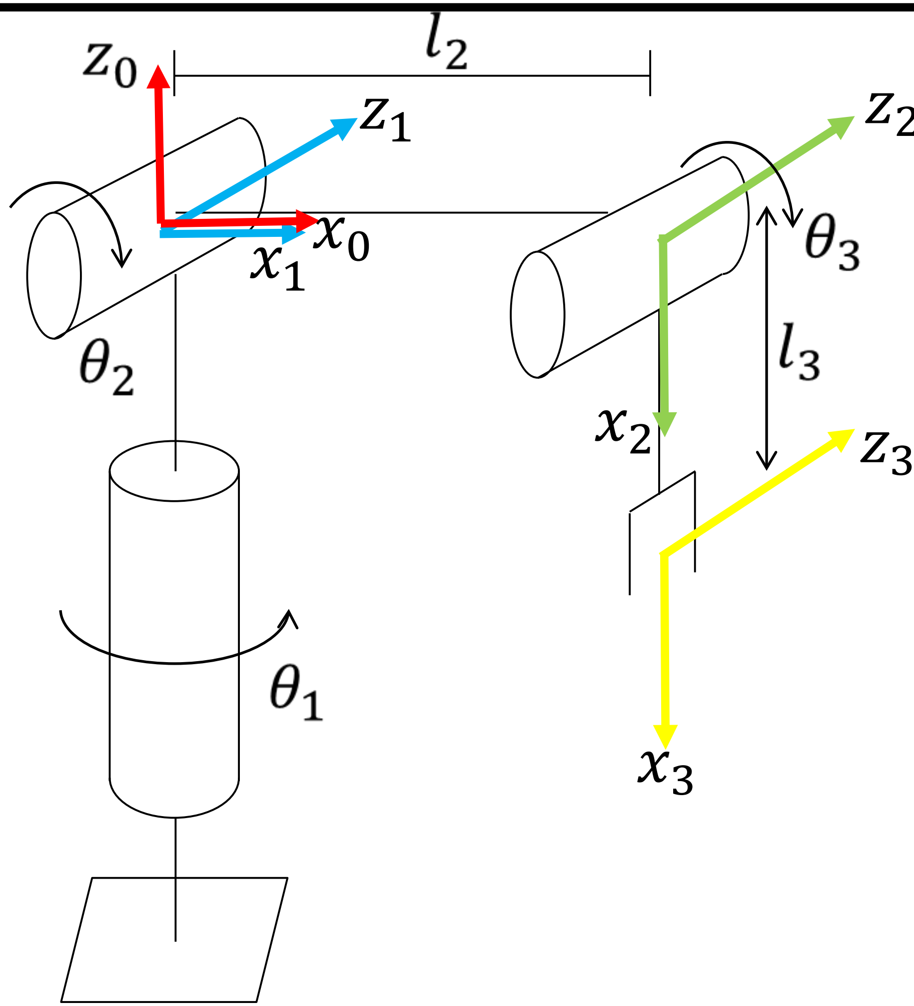


UCLA

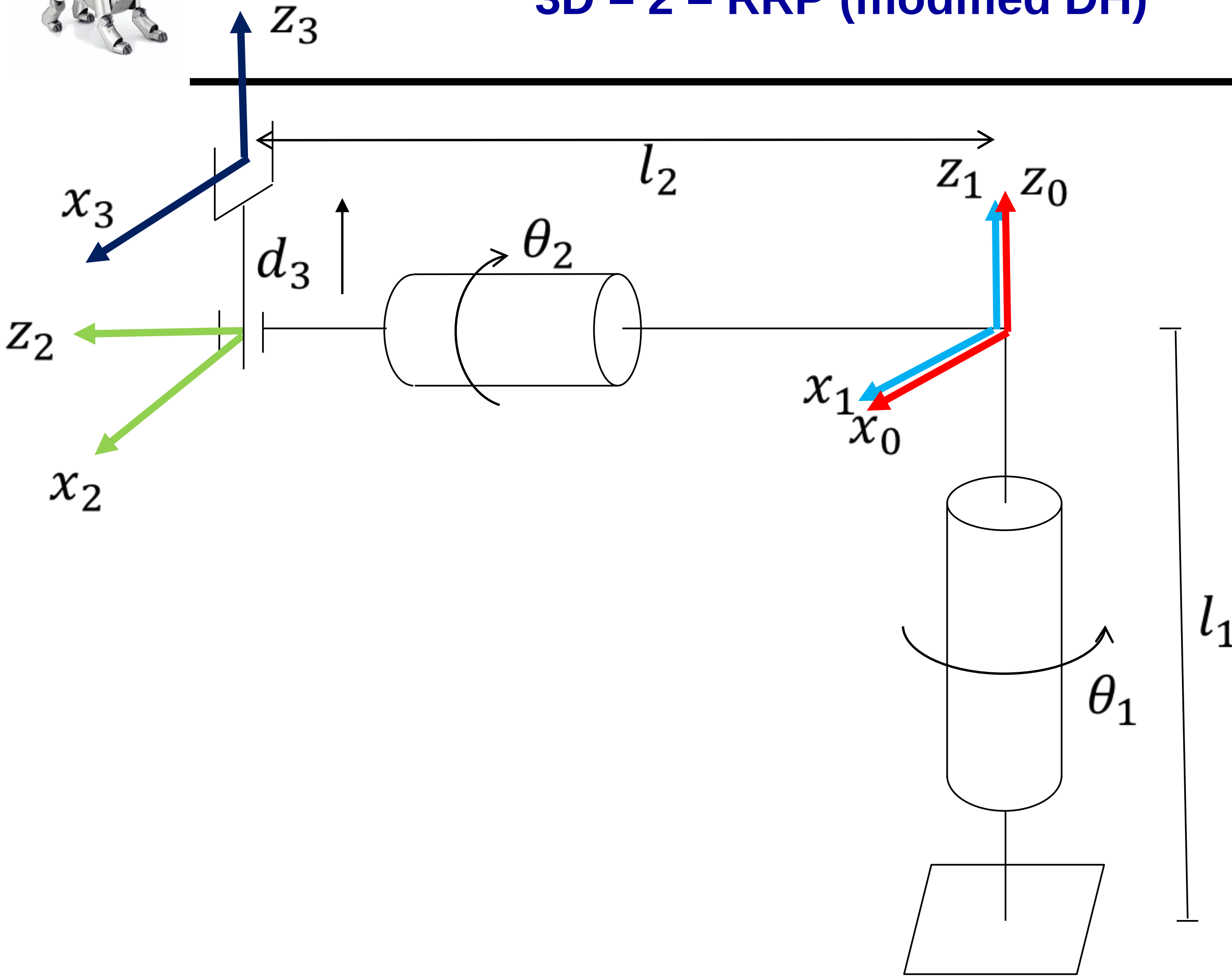
3D – 1 – RRR (modified DH)



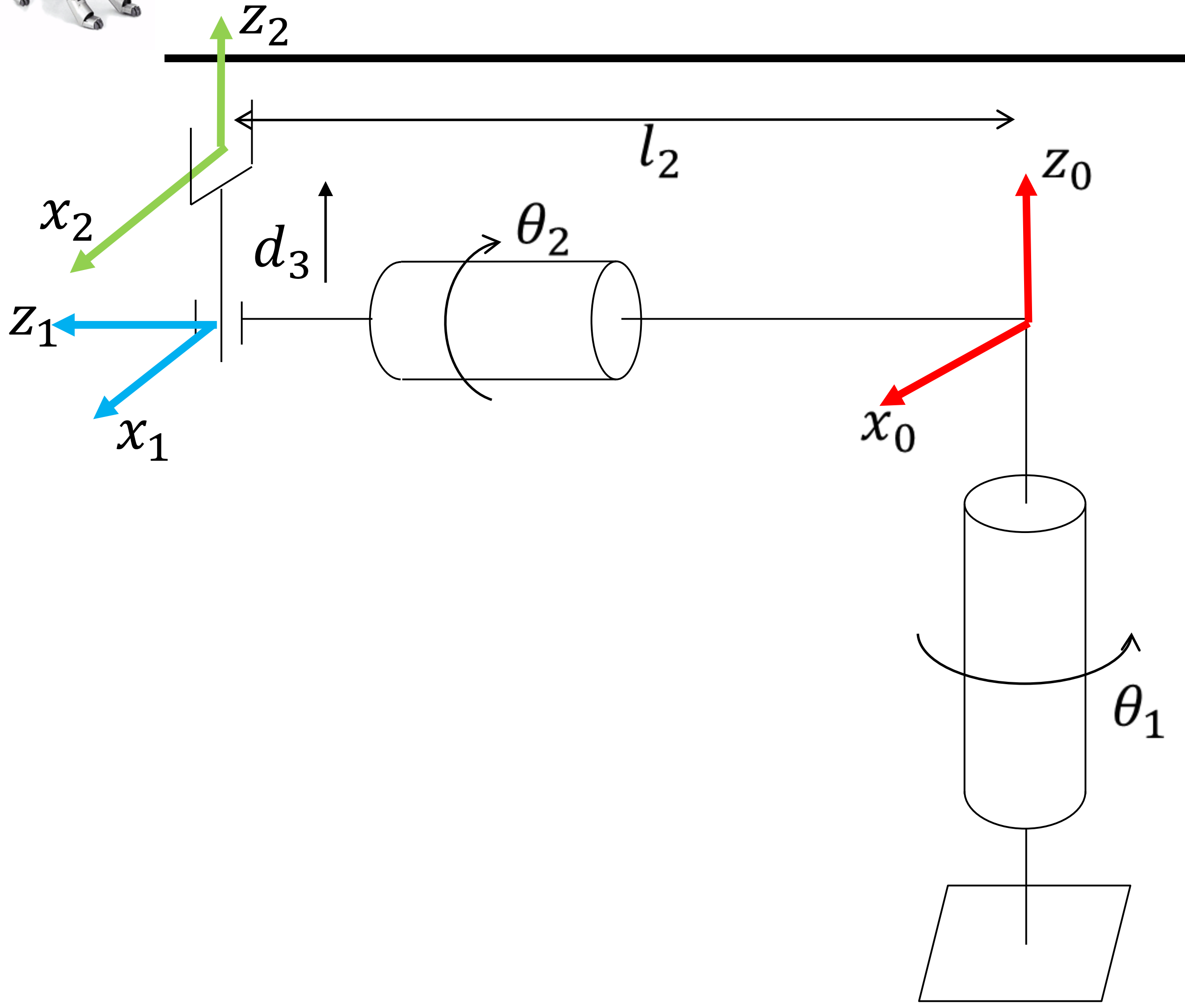
3D – 1 – RRR (standard DH)



3D – 2 – RRP (modified DH)

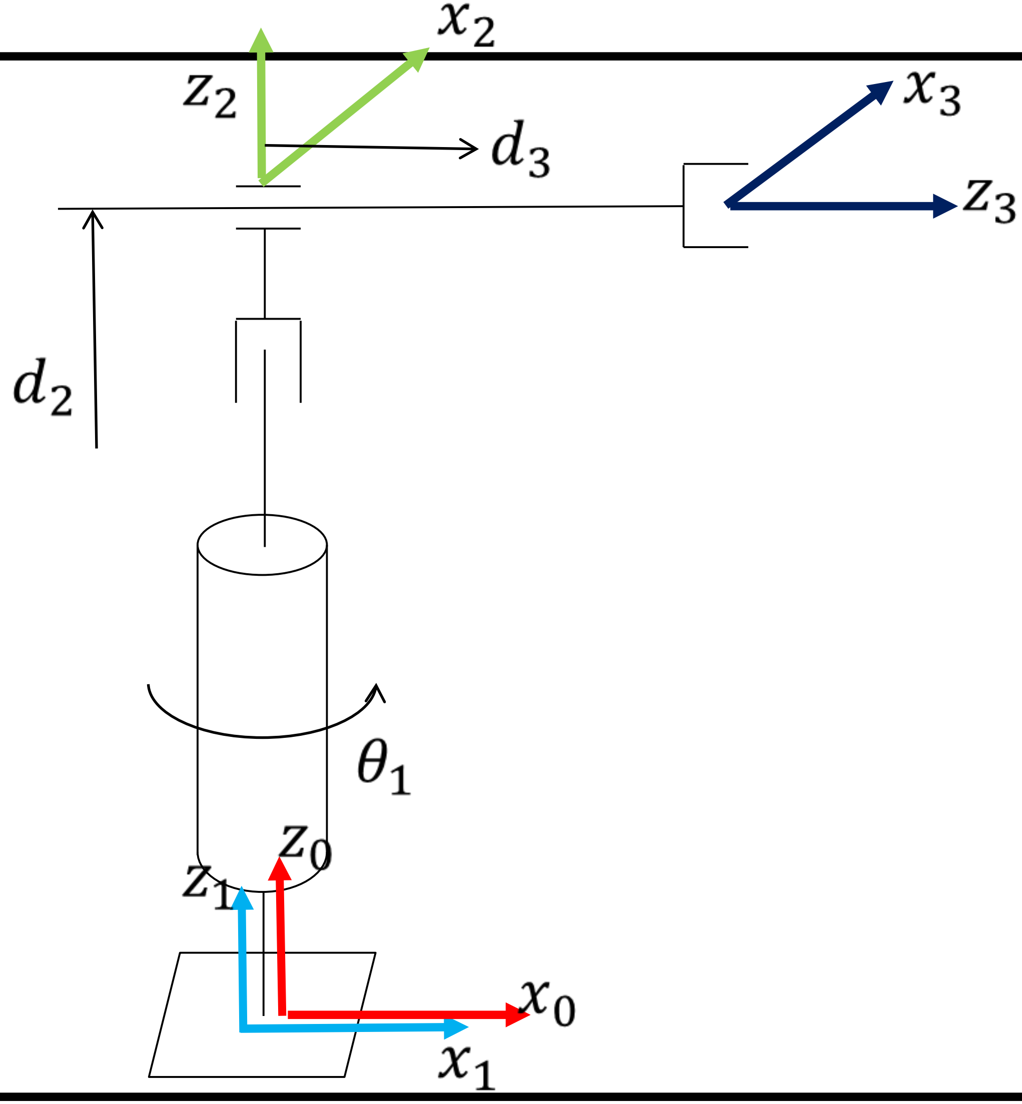


3D – 2 – RRP (standard DH)

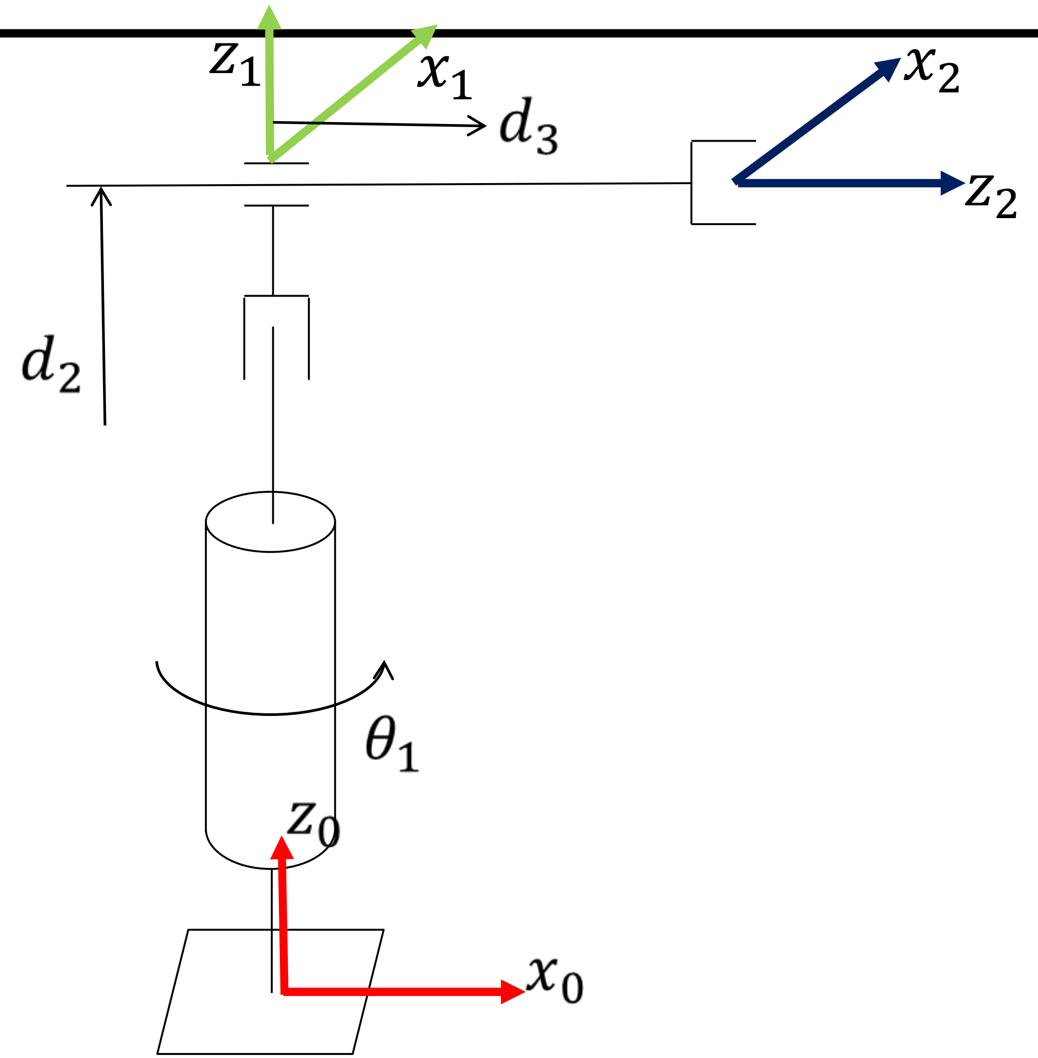


UCLA

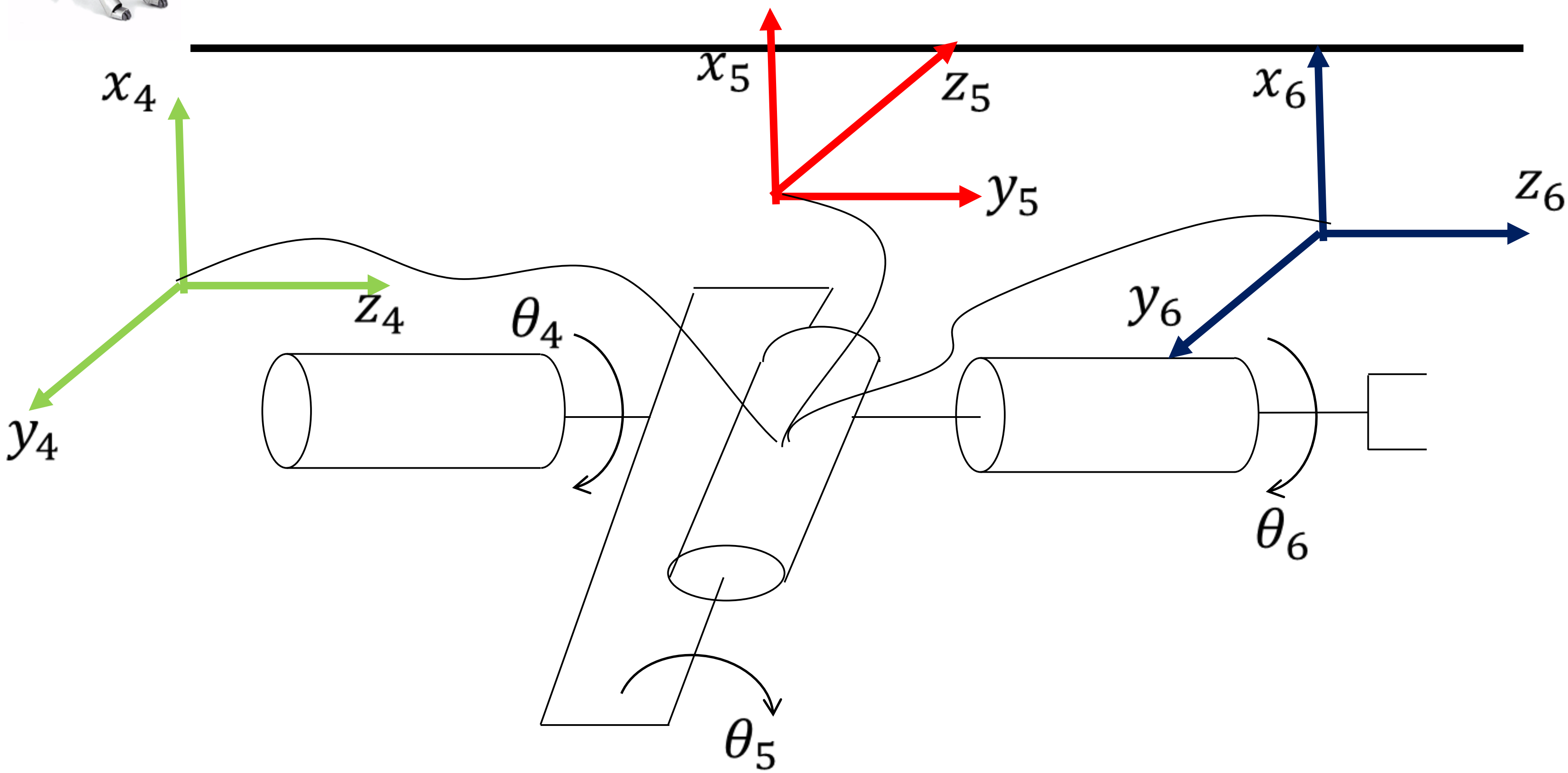
3D – 4 – RPP (Cylindrical Robot, modified DH)



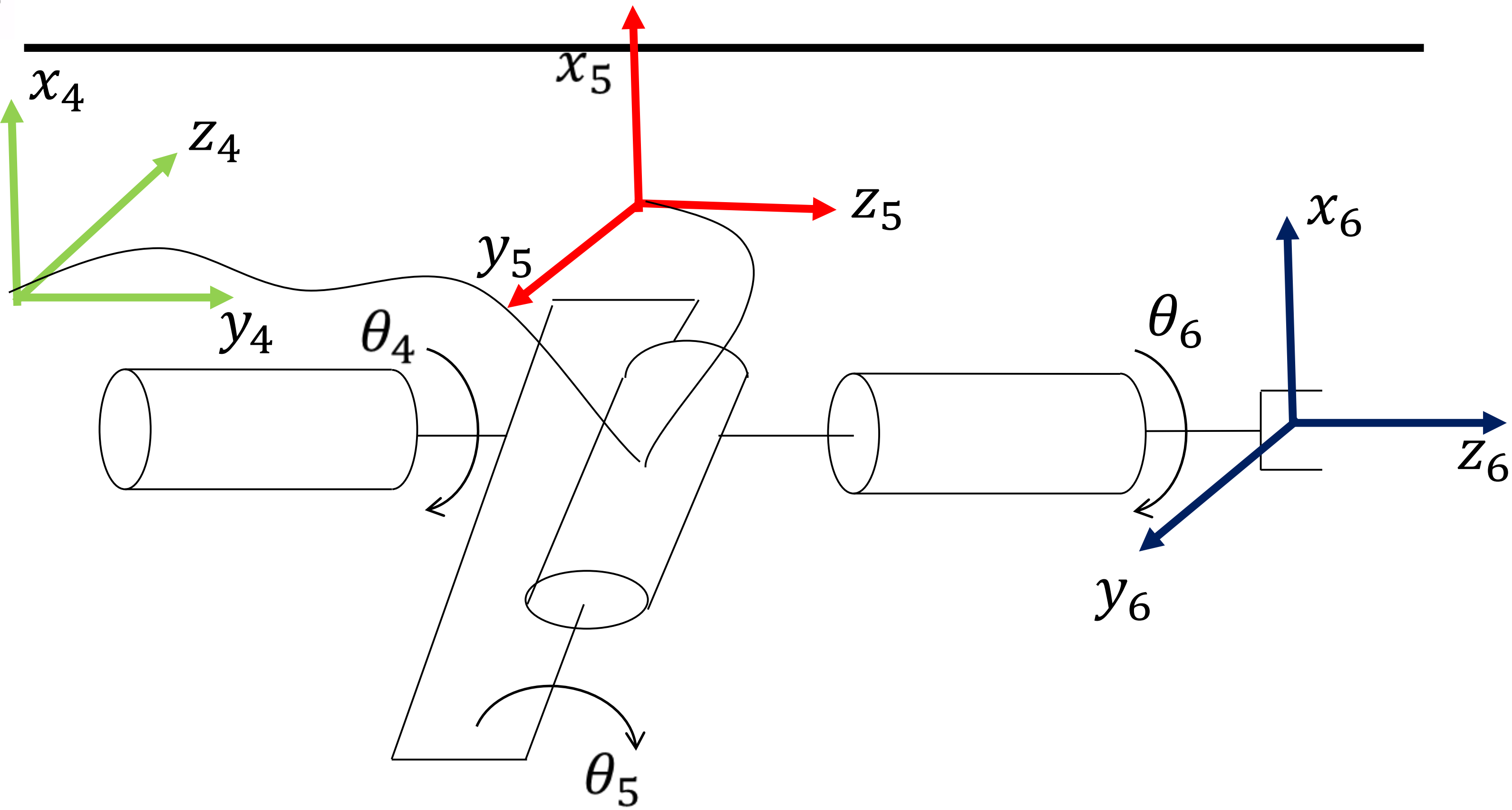
3D – 4 – RPP (Cylindrical Robot, standard DH)



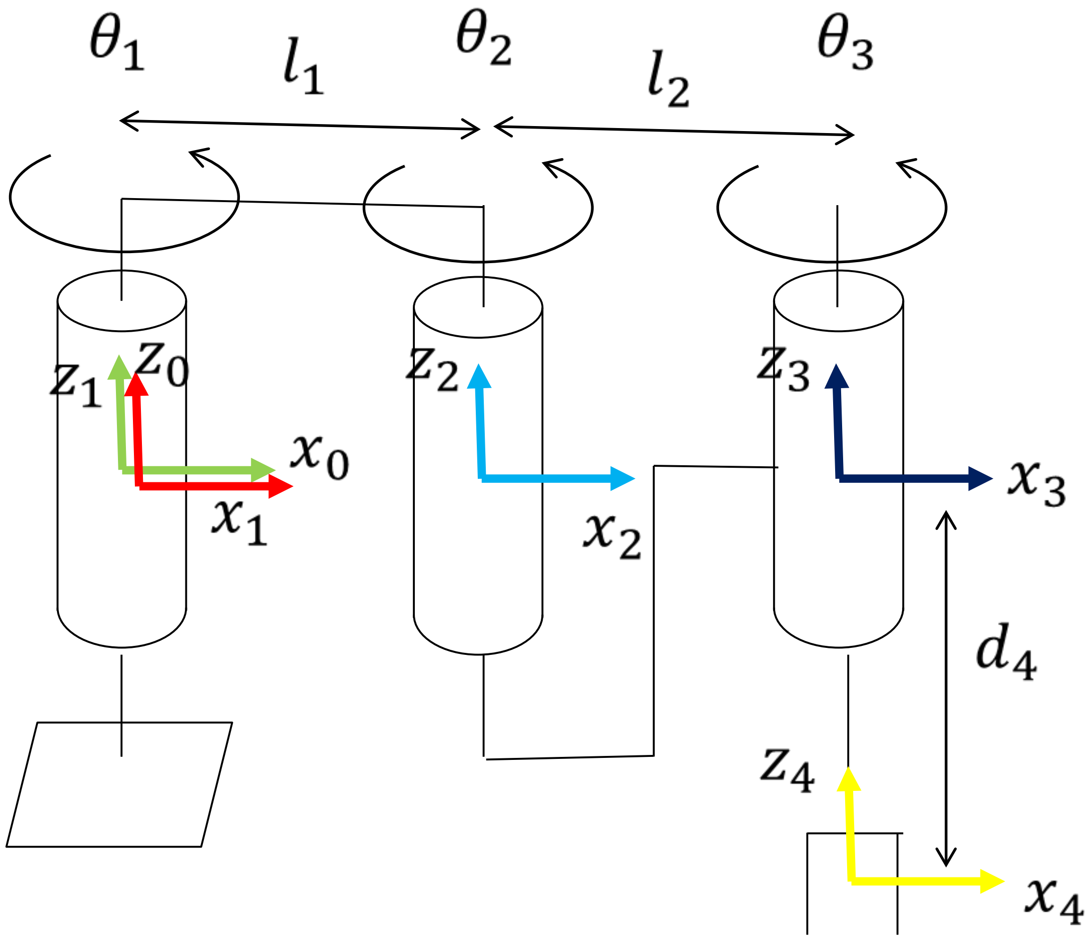
3D – 4 – RRR (Spherical Wrist, modified DH)



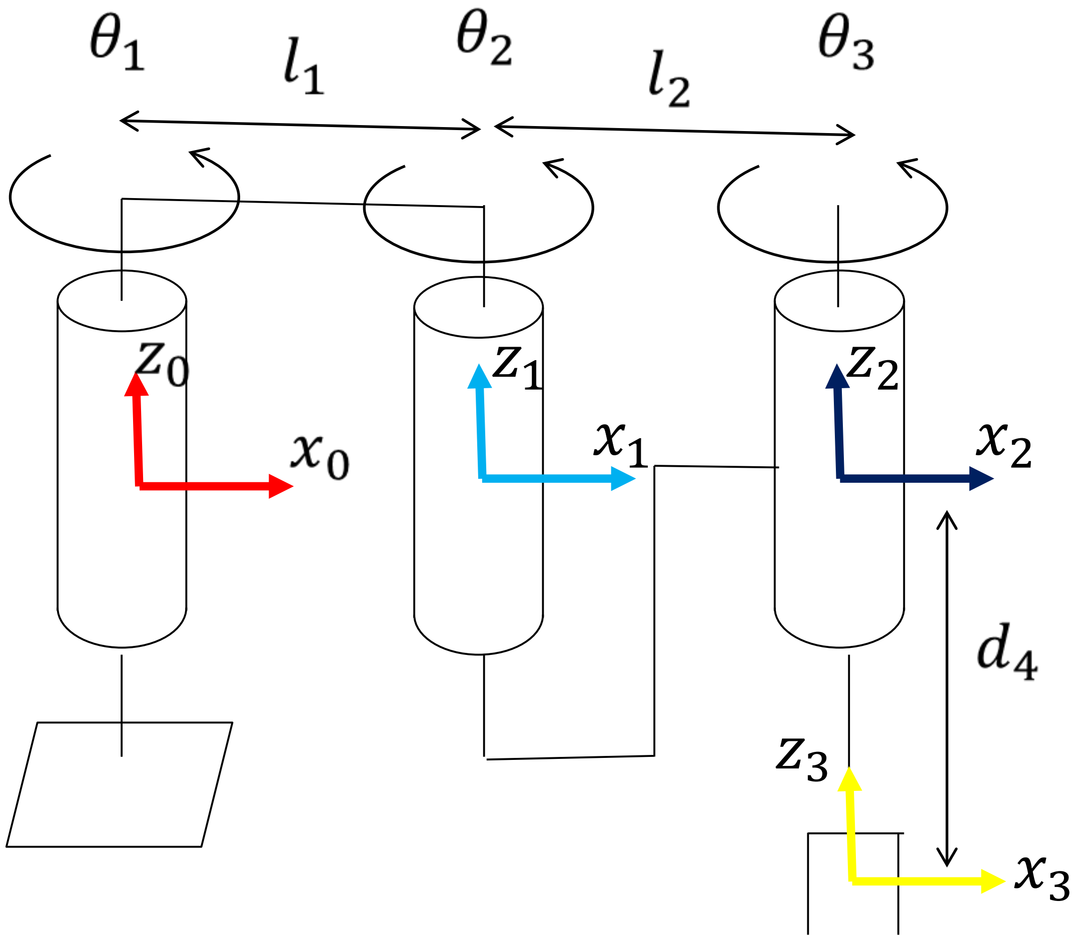
3D – 4 – RRR (Spherical Wrist, standard DH)



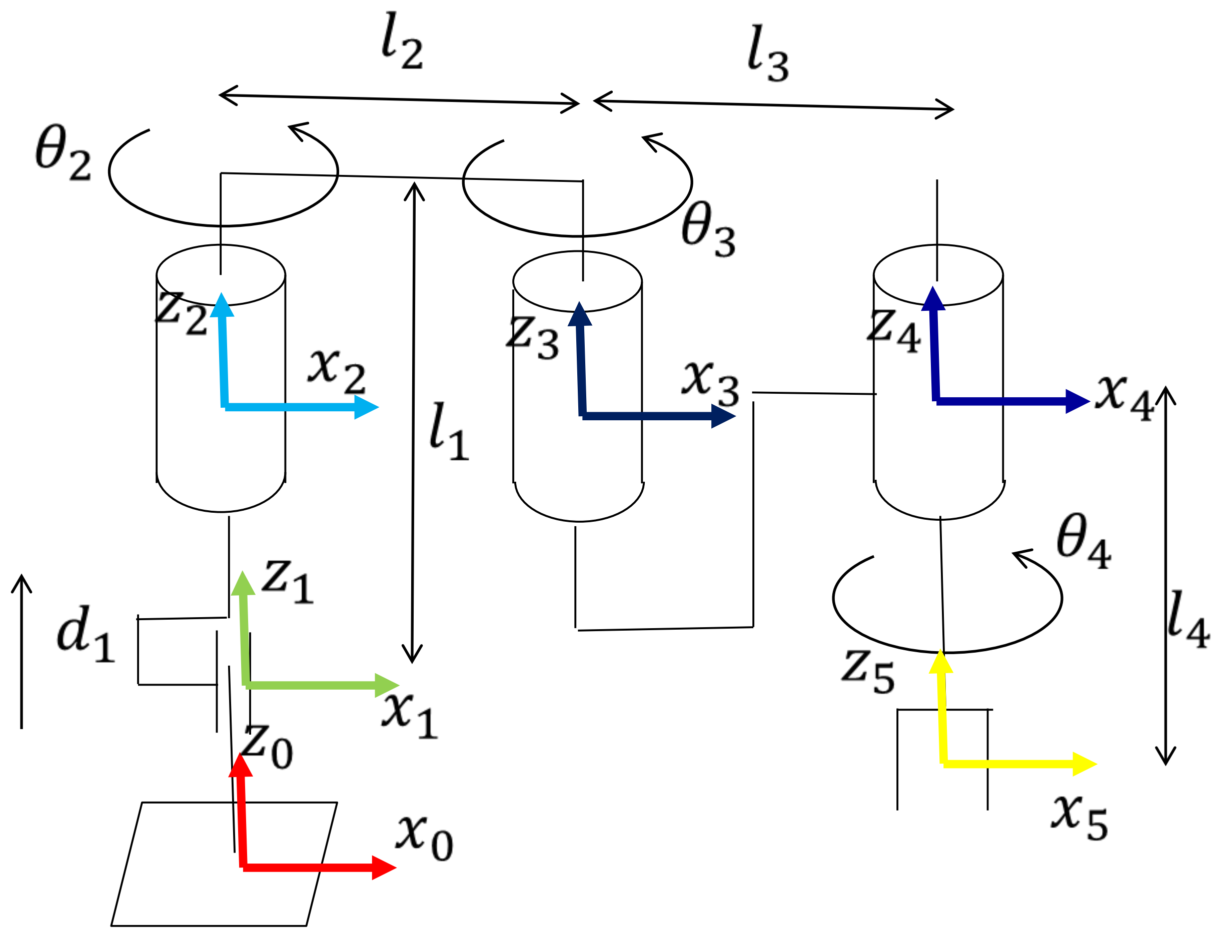
3D – 5 – RRRP (modified DH)

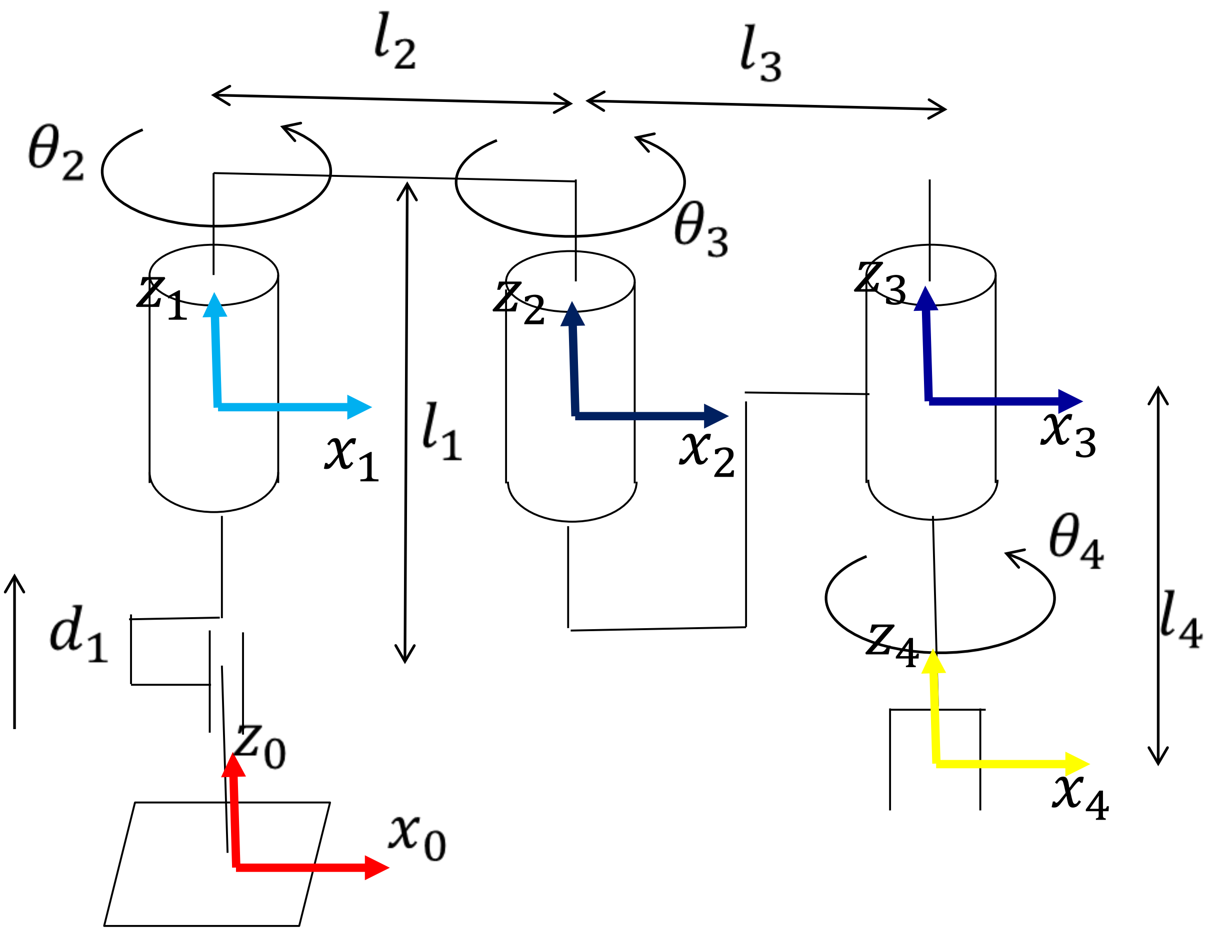


3D – 5 – RRRP (standard DH)



3D – 6 – PRRR (modified DH)

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l_3
θ_2
θ_3
θ_4
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z_3
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x_4
x_0
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l_4
d_1